

# Spatial Information-Based 3D GIS for Indoor & Outdoor Integrated Platform Development from CRETA Platform

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Manuscript submitted August 25, 2014; accepted March 12, 2015.

doi: 10.17706/ijcce.2015.4.6.397-408

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**Abstract:** Indoor & Outdoor spatial information technology closer to reality 3D space. So spatial information services market is growing now. A variety of information services and web-based content, to provide information services through the space. In addition, consumers make to direct spatial information service more than just a service provider. That means satisfy the needs of the consumer now. We have a lot of high quality smart devices. So, we will available to upload or share web.

In order to use the high quality image upload large amounts of processing is required. This study is indoor & outdoor build based on the 3D map data. And we will make to 3D builder 'CRETA Builder' and 3D viewer 'CRETA Vue'. There are management for integrated platform. We have to platform project name is 'CRETA'.

**Key words:** Spatial information service, CRETA platform, user participation, 3D GIS.

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## 1. Introduction

Buildings are getting bigger and more complex. The spread of smart devices, a wide range of services as a new chapter in the fusion of interior space is increasingly emerging as important. And, according to a report by the U.S. Environmental Protection Agency said, "For about 80% on average over the entire life takes place in the room. Moreover, there is a need of increasing indoor activities. Also disaster prevention against terrorism and accidents is an important issue that needs to be resolved.

In the field of spatial information process of building a real time digital map of the various types of information that must be collected. That service is spatial information in the field of outdoor and indoor space together without distinction to handle demand. Recently, spatial information technology service deployment from real 3D space, multi-dimensional space based information service and web-based content through a variety of service.

We are looking for the convenience of living a variety of techniques have been developed to be used in real life. This made possible the reality is that smart devices. Smart phone applications, instead of finding themselves on the existing can be. Typical examples, directions or ordering food, data search, contact search, public transport, such as arrival time of the service through the smart devices can be used anywhere, anytime. Percentage of smart phone users worldwide in 2012 and the end of the 1 billion people use around the world, given the population of 7 billion people 1 out of 7 people are using the smart devices.

Global companies such as Google, Apple and Microsoft have been constructing indoor spatial information.

They have been offering 2D indoor map and pictures (360° panorama) based indoor map provision. Now they are expanding the construction for indoor map from the U.S to worldwide. These services are predicted about 120,000 places in 2016.

In this study, many LBS services can be provided based on indoor spatial information. With the rapid development in hardware and software of wireless communications, applications of real-time positioning systems have been widely used; among them the GPS is the most popular. Creating 3D indoor maps is getting even more useful by providing maps for indoor spatial information. People needs for LBS services for their safety and convenience through the integration of indoor spatial information. So, we make to indoor & outdoor integrated 'CRETA' platform.

## **2. Spatial Information Technical Trends**

There are at least 170 companies today working on indoor location, indoor maps, building tracking and indoor navigation add to outdoor position. The growth of this market has been impressive over the last 10 years. Indoors is the last mile and the next frontier for the location services market. Indoor maps emerged rapidly in 2009 as started up such as Point Inside, Micello and Nokia. Released their indoor content, while indoor mapping data is available for indoor navigation applications, associated location determination is still a challenge. A number of tagging & infrastructure based technologies can deliver to precise indoor location, but it is tough to make these solutions ubiquitous.

### **2.1. CCTV Image Processing to Outdoor Map**

Image data representative of the services offered by the MS of the 'Photosynth'. Fig. 1 shown by 'Photo-Synth' in the case of individuals who hold multiple pictures, similar to the actual appearance by placing shall automatically complete three-dimensional picture. Three-dimensional pictures on-line store, and the location of the photos on the map by inserting has been able to show to other users.

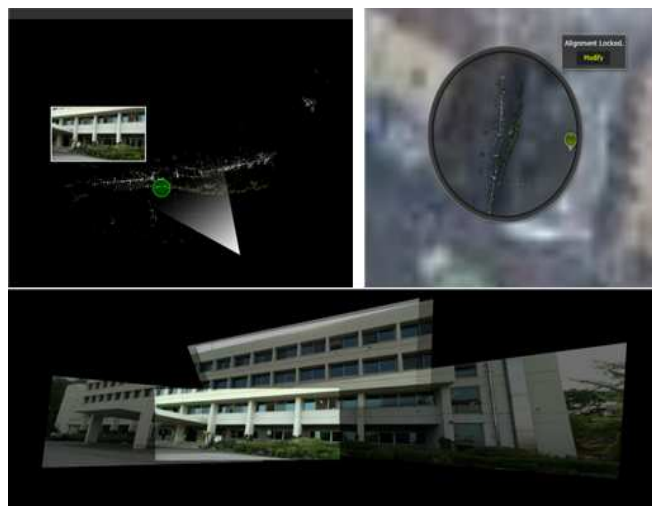


Fig. 1. 'Photosynth' 3D point cloud and inserted on the map (above), 3D photos (below).

Multi-dimensional real-spatial information (hyper-live map) to in the image data obtained through the Point Cloud to 3D Reconstruction purpose of the study, performed experiments by CCTV.

Experimental results establish the structure only when recording CCTV, when shooting closed areas or shaded areas 50% due to the building was possible, To compensate for this, the video camera, or smart phone video by adding the results of building CCTV video was more effective than just that building. Fig. 2 shows the Konkuk University main building with CCTV video camera image is using that constructed.



Comparing Service Delivery Paradigms

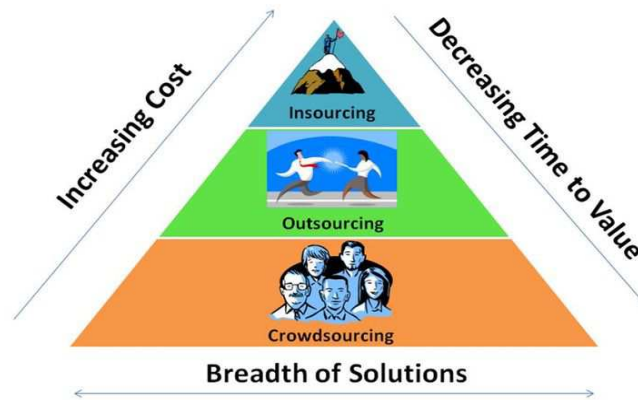


Fig. 4. The advantage of crowd sourcing.

## 2.4. Crowd Mapping

As said, crowd mapping is designed and built by the team behind Ushahidi, a platform that was originally built to crowd source crisis information. As the platform has evolved, so have its uses. Crowd mapping now allows users to set up their own deployments of Ushahidi without having to install it on a web server. Since its release in 2010, prominent deployment of crowd mapping have documented the global 'occupy' protests and the 2011 London anti-cuts protest [5].

On December 31, 2010, the Ushahidi team announced crowd mapping: Checkins, a geo-social add on to Crowd mapping that allows users to create a white label alternative to sites like Foursquare and Gowalla [5] [6]. Rather than filling out submission forms online, Checkins allow crowd mapping users to expedite data entry to their deployment, focus first on location and adding more detailed information later [7]. Ushahidi describes the effort as 'checkins with a purpose'. Fig. 5 shows crowd mapping service.

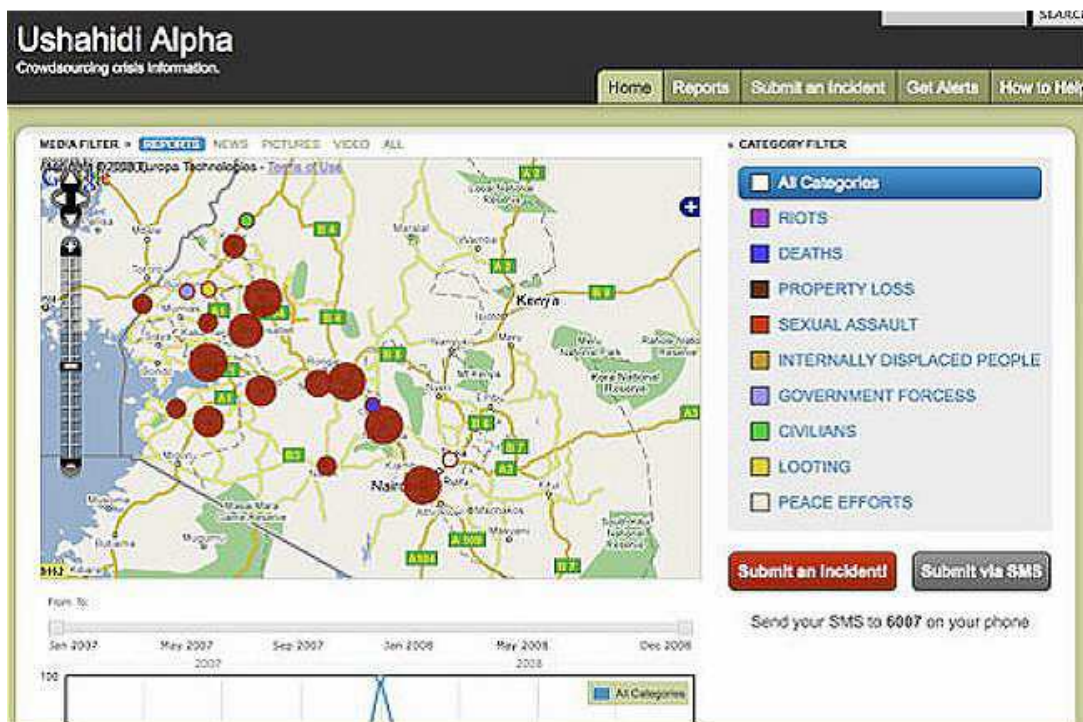


Fig. 5. Crowd mapping (Ushahidi).

## 2.5. User Participation

Wikipedia users to make their way directly participated map programs are gaining popularity recently. Focusing on user participation in Wikipedia map Global Positioning System (GPS)-equipped people to use a smartphone without any prior knowledge help us be able to create a map of the world. Participation typically made of an open-source map 'Waze' and Open Street Map there [8].

Israel Tal Aviv 'Waze' for the first time in 2006, began. Fig. 6 shown by 'Waze' logo. Users are not marked on the map into a dead end when the Wise stood no way connected to the place on the map to display the next place to visit for people who can help. 'Waze' is now the driver of the 14 million people worldwide and is used to edit the map and 45,000 people living in 5,000 people in his area manager to verify the accuracy of the map is active [8].



Fig. 6. 'Waze' logo ([www.waze.com](http://www.waze.com)).

Open Street Map is a 'Waze' was born with a similar purpose or non-profit model is more like Wikipedia. Open Street Map is like Wikipedia, which anyone can add information to connect to the home page and can be modified because it is free to use. Usage of open street map homepage and searching for the place is similar to Google Maps. However, unlike Google Maps and Open Street Map is a map, not just anyone can use without having to pay a geographic information features [8].

Recent popular location-based social network services company Foursquare have the same characteristics of the open street map to identify the user where their friends are staying open, make sure that you had to use a street map unveiled last month.

Disaster relief organizations are also 'maps of the terrain is changed just change' increasingly rely on participatory map. Earthquake in 2010 significantly changed the topography of the entire country rescuers in Haiti is that using the example of the open street map. Nine trillion won at the time of the Haiti relief efforts using real-time information to modify the map where the terrain is changed when it arrived and prayed to inform the open street map.

Jonathan Bennett, open street map users "that there is no other way to create a map from the open street map is not inferior to the rate of progress," he said [8].

## 3. High Quality Image Data Acquisition Methods Research (To CRETA Builder)

In the field of spatial information process of building a real time digital map of the various types of information that must be collected. That service is spatial information in the field of indoor and outdoor space together without distinction to handle demand [9]. Recently, spatial information technology service deployment from real 3D space, multi-dimensional space based information service and web-based content through a varieties of services [10].

South Korea government makes the 3D map by 'V-world'. 'V-world' seems like 'Google Earth'. And 'Naver' and 'Daum' map service in the aerial view, real photo view or normal view [9].

We are looking for the convenience of living a variety of techniques have been developed to be used in real life. This made possible the reality is that smart devices. Smart phone applications, instead of finding themselves on the existing can be. Typical examples, directions or ordering food, data search, contact search,

public transport, such as arrival time of the service through the smart devices can be used anywhere, anytime. Percentage of smart phone users worldwide in 2012 and the end of the 1 billion people use around the world, given the population of 7 billion people 1 out of 7 people are using the smart devices [11]. This spread is the spread of smart devices, a wide range of services as a new chapter in the fusion of interior space is increasingly emerging as important. And, according to a report by the U.S. Environmental Protection Agency said, "For about 80% on average over the entire life takes place in the room" [6].

### **3.1. Indoor GIS**

GIS is geographic information are integrated into a quantitative one was indifferent about the human scale of the room. So interior space contains a symbol of various services and information, or an interface (Tag, POI, etc.) are present but there is no information about its real [12].

Focusing on recent academic to integrate BIM and GIS research is actively underway. GIS is based information, BIM provides the details of the center of the building. However, the level of detail is very large grid. Indoor GIS & BIM are in nature having a point of use, and service-oriented information structure. The interior is the use of all buildings, scale, design, location, depending on the various and varied interior spaces. Scale, purpose, design, and location are different according to the morphological characteristics difficult typed. It means necessary to build an optimized DB. Stairs, escalators and elevators are difficult to define in addition to the basement floor, including a 3D information space to be implicated. Such as underground nest and the oldest man stayed in most of the telecommunication spaces are generated. This information is interior space concern the future of global companies.

### **3.2. 3D Modeling Builder (CRETA Builder)**

Apart from other architectural modeling tools, CRETA Builder based on architectural components is optimized for how easy people convert physical space into 3D modeling data to provide the architectural services, especially, indoor services such as facility, space, surveillance, lighting and energy management. Not only does it make anyone use 3D model easily and comfortably, it also enables to integrate with any other software and systems.

#### **3.2.1. Exterior modeling algorithm**

In this study, user participation to indoor & outdoor build to 3D map. By default, the collected to data, make to 3D modeling experimental. The collected to data by all use of the smart camera, 3D construction make to 'MATLAB' code by DLT technique. 'MATLAB' code is exist used to made DLT technique on last year (Fig. 7).

So, we want to the collected to 3D data, we choose to place. This place is exist experimental at 'Ankara House' at Seoul, Korea. This house is made by Turkish architecture.

#### **3.2.2. Take a photo**

Original studies built 3D data was used to CCTV camera. However, this study is collected to CCTV data and add to camera user picture at any position, so we will make to high quality 3D map data. That collected to smart camera were taking pictures (Fig. 8).

#### **3.2.3. Indoor collected image data**

This study is different from previous studies, indoor & outdoor built to 3D map about user participation to spatial information service. So, collected to data for smart camera at any positions. It is used in a Virtual Builders program 'CRETA Builder' through the indoor space will be 3D modeling (Fig. 9).

This study will to provide indoor & outdoor spatial information service. And it offers to user participation, a better way accurate information and high quality spatial information service that the consumer is not boring and difficult to purpose.

The Fig. 10 is the 'CRETA' Builder program through the room look like the work of modeling.

```

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%
% Reconstruction using DLT method
% Programmed by D. S. KIM (2013, 03, 05)
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%

clear all
clc

% 3차원 좌표 입력 (14개 포인트 입력)
x = [218.507 218.544 219.241 280.086 268.801 235.621 260.238 243.595
226.382 230.725 232.280 227.706 226.651 222.968 239.202 234.932 217.580
219.529 219.676 215.738];
y = [90.230 90.210 85.285 26.081 28.969 59.435 24.821 39.080 56.584 61.546
57.496 60.743 57.640 60.750 36.683 37.665 60.589 60.548 57.612 53.984];
z = [311.363 310.063 308.929 319.866 315.686 308.270 302.028 303.466
303.855 311.755 315.716 309.721 308.625 312.123 333.571 334.197 315.719
309.577 309.600 302.796];

% 대응되는 영상 2차원 좌표값 입력 (왼쪽 영상)
u_left = [258 243 594 736 850 956 1046 1168 1346 1069 1120 1195 1309 1379
1307 1398 1618 1537 1592 1858];
v_left = [22 171 383 584 643 716 940 908 890 543 422 624 681 497 84 30 294
601 618 943];

% 대응되는 영상 2차원 좌표값 입력 (오른쪽 영상)
u_right = [78 61 439 663 777 864 976 1091 1250 971 1024 1096 1211 1274 1220
1308 1504 1428 1486 1752];
v_right = [47 196 406 606 664 736 959 925 905 562 440 640 697 512 102 48 309
614 631 951];

if length(u_left) == length(x)
    for i=1:length(u_left)
        X_left(2*i-1,:) = [x(i) y(i) z(i) 1 0 0 0 0 -u_left(i)+x(i) -u_left(i)+y(i) -u_left(i)
+z(i)]; % 최소제곱 조정을 위한 DLT 매트릭스의 첫줄임
        X_left(2*i,:) = [0 0 0 0 x(i) y(i) z(i) 1 -v_left(i)+x(i) -v_left(i)+y(i) -v_left(i)+z
(i)]; % 최소제곱 조정을 위한 DLT 매트릭스의 두 번째 줄임
        Q_left(2*i-1,:) = u_left(i); % 최소제곱 조정을 위한 DLT 매트릭스의 오른쪽 매트
릭스 첫줄임
        Q_left(2*i,:) = v_left(i); % 최소제곱 조정을 위한 DLT 매트릭스의 오른쪽 매트
릭스 두 번째 줄임
    end
    for i=1:length(u_right)
        X_right(2*i-1,:) = [x(i) y(i) z(i) 1 0 0 0 0 -u_right(i)+x(i) -u_right(i)+y(i) -
u_right(i)+z(i)];
        X_right(2*i,:) = [0 0 0 0 x(i) y(i) z(i) 1 -v_right(i)+x(i) -v_right(i)+y(i) -v_right
(i)+z(i)];
        Q_right(2*i-1,:) = u_right(i);
        Q_right(2*i,:) = v_right(i);
    end
end

```

Fig. 7. 3D reconstruction of DLT technique (MATLAB code).



Fig. 8. Take a photo at 'Ankara House' Seoul, Korea (Yongwon Cho).



Fig. 9. Take a photo at 'Ankara House' Seoul, Korea.



Fig. 10. Modeling program 'CRETA Builder'.

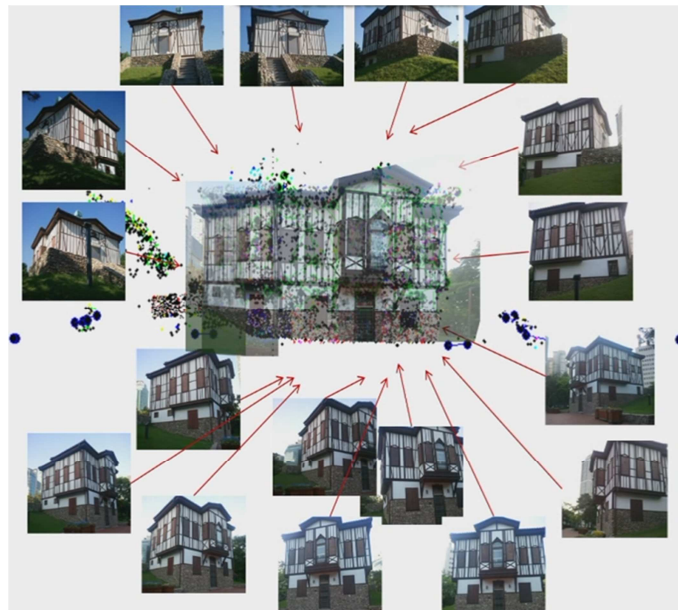


Fig. 11. Modeling program 'CRETA Builder'.

In many parts of panorama pictures taken from any locations to 3D modeling was made it. The Fig. 11 that is possible based on this 3D modeling of user participation shown.

#### 4. Development to 'CRETA' Platform

##### 4.1. What Is 'CRETA' Platform?

Currently, spatial information technology have to look at home and abroad, seamless potted 3D spatial information of the data in the service quality, size, and format such reasons can't be used.

The reason is that the development of the provider's format is different for each platform, as well as quality difference, where the amount of data and that can be processed easily in Big Data based technology that has not been established yet.

In particular, indoor & outdoor spatial information technology service development so far has been carried out separately. Accordingly, integrated platform mounted on the model in order to convert the potted in conjunction with techniques and products were developed.

The basic process is CRETA Platform divided into three phases. Construction shape information based on a CAD drawing step is to calculate the standard drawings, which maps to the main structure for building, facility location, and converts the extracted DXF LOD2 and LOD4 are construction based on the structured object map. Object Class Units (space, walls, pillars and etc.) to build 3D maps, texture application, apply to the placement of facilities (Fig. 12).

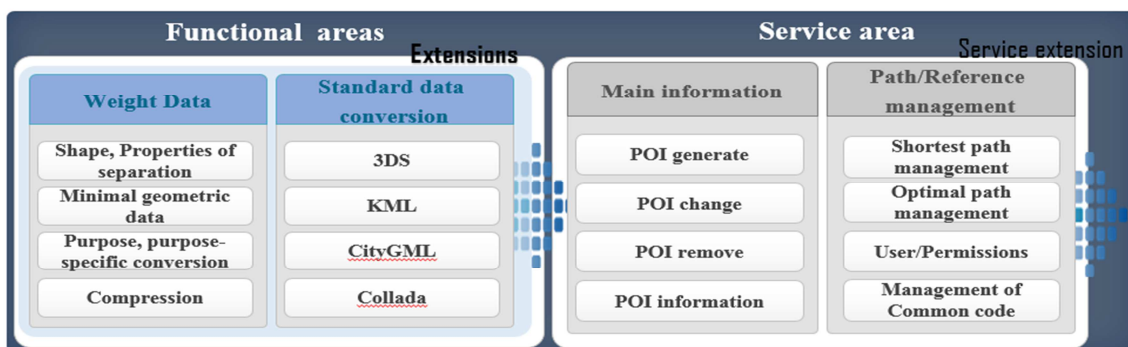


Fig. 12. 'CRETA' Platform functional & service area.



Also, LOD integrated in building a map for indoors surface point cloud data acquired through measurement LiDAR data over the generated noise and distortion correction. And through a process of matching the data pre-processing 2D vector-based maps (LOD1) or 3D polygon map (LOD3) is made.

In the case of 2D vector maps indoors interior space mapping and using the results of the scan, 3D polygon map of the indoor space, the 3D modeling / Geometry objects for structuring certain specified. The LOD1, LOD3 and LOD4 as mentioned above, the import can. LOD4 consisting of the map, the structured object, Geo-referencing the relative coordinates to absolute coordinates must be measurements made on the basis of the reference point information.

Non-geometric information in the construction phase, the preliminary research POI import and POI information about major / or editing of the coordinate indoor space for directions Topology service for creating and editing the data generated through the relationship expressed by the network (Fig. 13). 4.2 CRETA Builder saves to CRETA Platform.

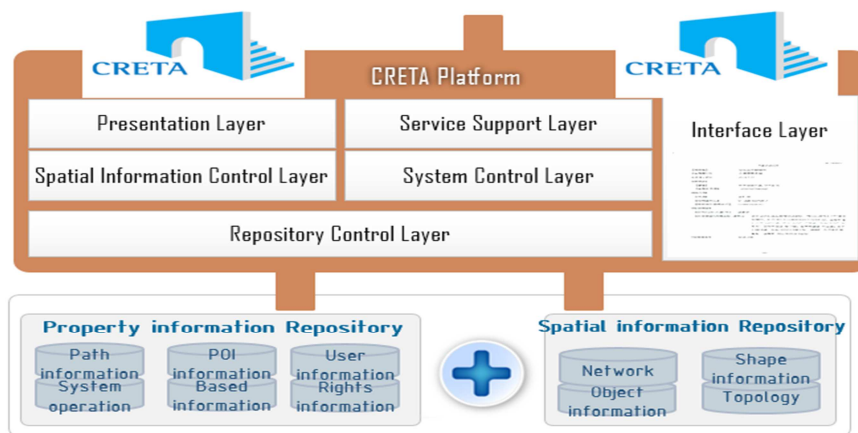


Fig. 13. 'CRETA' Platform area.

Several types of product features are involved in CRETA Builder (Fig. 14).

- 1) Automatic conversion: 2D plans (.dxf) or images of buildings which were preprocessed are automatically converted to 3D model using the function of underlay.
- 2) Topology authoring and editing: The relationship in between different kinds of rooms is used for the optimized way-finding and event handling service.
- 3) Compatibility for global standard: 3D building models done by CRETA Builder is compatible with Autodesk's (.dxf), OGC's (.kml) and (.ifc) as well as X and 3ds file format that can apply for either game engine or virtual reality.
- 4) Editing component properties: The properties of architectural components such as slab, wall, door, facilities and etc. are editable.
- 5) Space authoring for the building information: Both geometric and semantic information of buildings are dealt with in CRETA Builder.
- 6) Simple style modeling for outdoor map: Expand to a variety of services through the authoring of outdoor space simple and intuitive (Fig. 15).



Fig. 14. 'CRETA' Builder area.

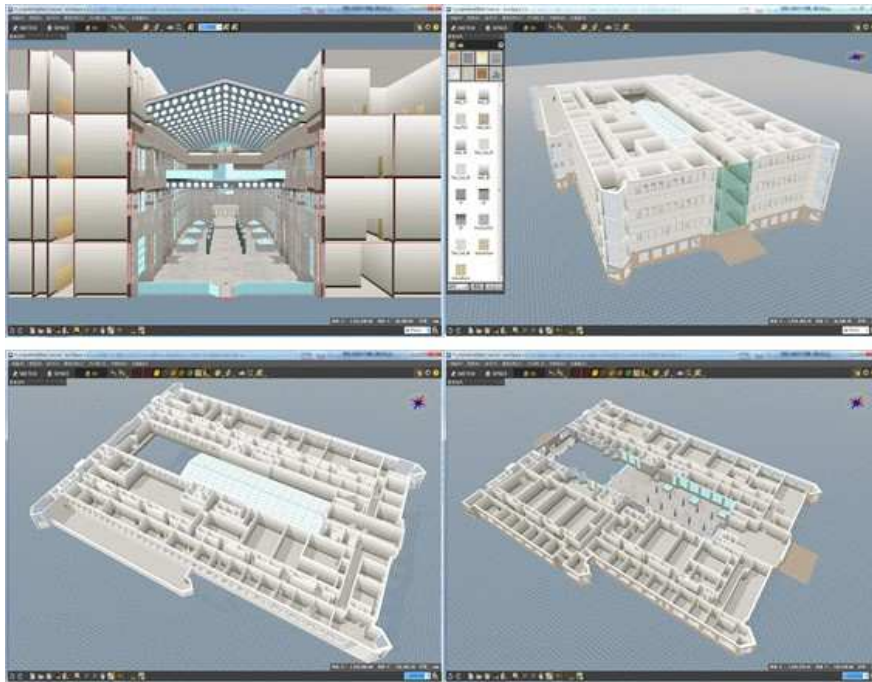


Fig. 15. CRETA Builder test modeling (Yonsei University, Korea).

#### 4.2. CRETA Vue to CRETA Platform

CRETA Vue is built on 'Unity web 3D player'. CRETA Vue features are loading to only .SBM data, processing to GKXML version and renewal API. (Now on CRETA Vue ver. 1.6) And then, CRETA Vue is service about web and mobile (Fig. 16). Because through a variety of equipment, plan area and to provide information developed.

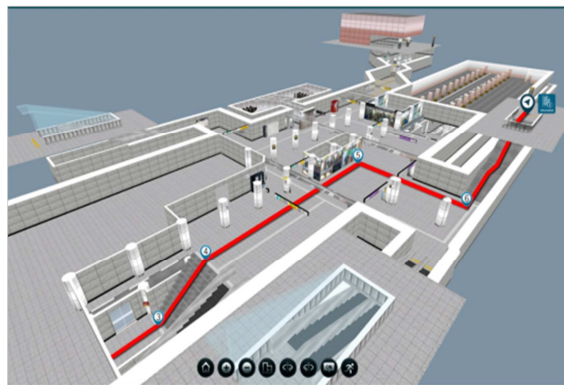


Fig. 16. CRETA Vue web service (Subway station, Seoul).

### 5. Scalability

CRETA Platform trial run trial services information system operating at the same time as the improvements are intended to collect and reflect.

#### 5.1. Building Tools POI

Enter for POI information to trial level was developed.

Indoor & outdoor POI integrated network was applied to the implementation of the platform (Fig. 17).



Fig. 17. POI category.

## 5.2. Range of Web Service

On the indoor information about indoor name and POI information was aimed at visualizing. The basic 3D visualization features.

## 5.3. Range of Mobile Service

Android OS based services was a priority.

## 6. Simulation Results

We purposed that provide to indoor & outdoor spatial information service for CRETA integrated platform. So, this CRETA Platform service is focus to for the people. Make to 3D modeling is first. But, this suggest is shows very difficult. Because of show to exact location and indoor & outdoor fusion viewer service is engineer's effort. So, we had problem solved and now on we show indoor & outdoor integrated CRETA Platform service (Fig. 18).

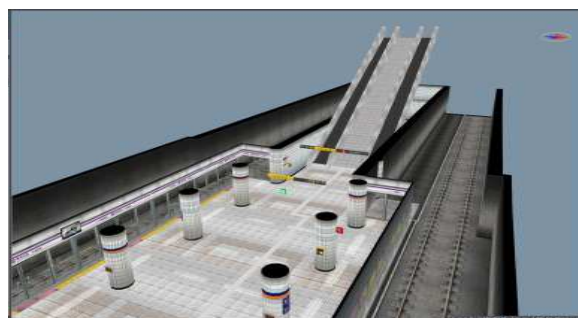


Fig. 18. CRETA platform service (Subway station).

## 7. Conclusions

There are many future plans indoor & outdoor integrated platform. But we have do this. This CRETA Platform.

Finally, 'CRETA' Platform based 3D spatial information consists of space authoring (CRETA Builder), space operation (CRETA Manager) and space visualization (CRETA Vue). It carries out more space values and new space experiences with realistic 3D technology. Our professional solutions at business, service and

technology raise your values up through new perspective of space, challenge and integration with technology.

## Acknowledgment

This research was supported by a grant (11 High-tech G11) from Architecture & Urban Development Research Program funded by Ministry of Land, Infrastructure and Transport of Korean government.

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